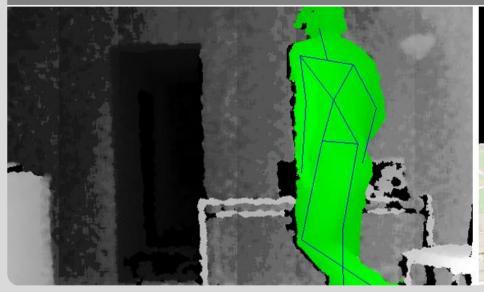
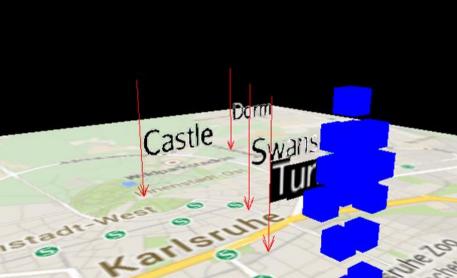


Stream Reasoning in Mixed Reality Applications

Andreas Harth Joint work with Felix Keppmann, Steffen Stadtmueller and Tobias Kaefer Stream Reasoning Workshop, Vienna, November 2015

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KIT – University of the State of Baden-Wuerttemberg and National Research Center of the Helmholtz Association



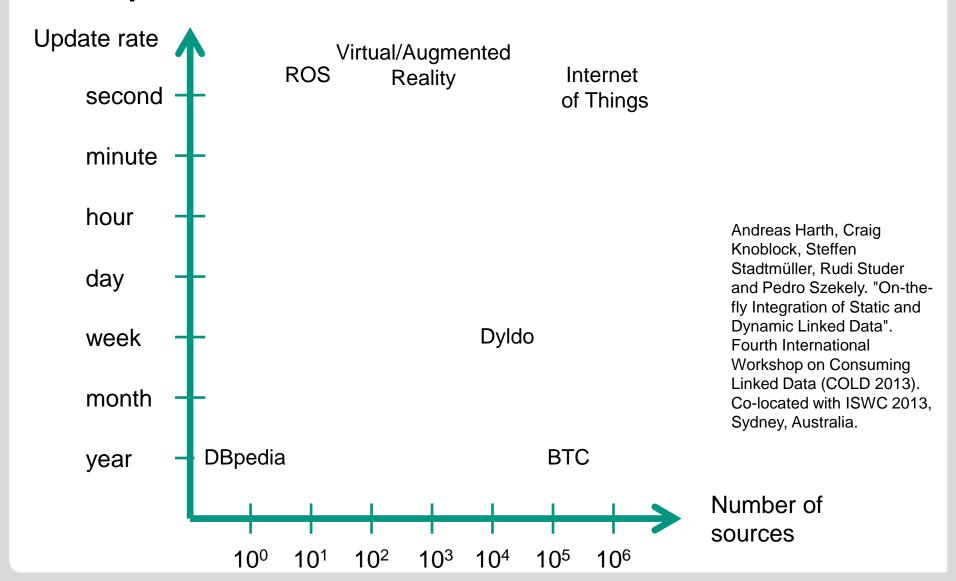
Outline



- Motivation
- Representation and Interface
- Architecture
- Applications
- Conclusion

Motivation: Data Integration and System Interoperation at Scale



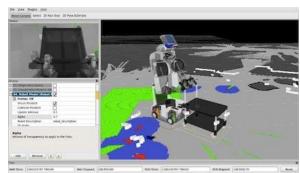


Representation and Interface

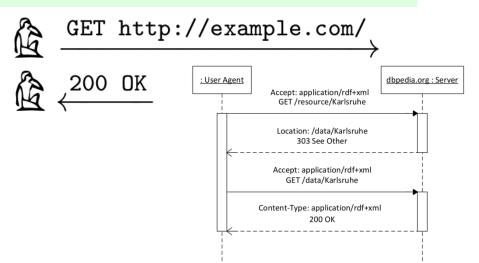


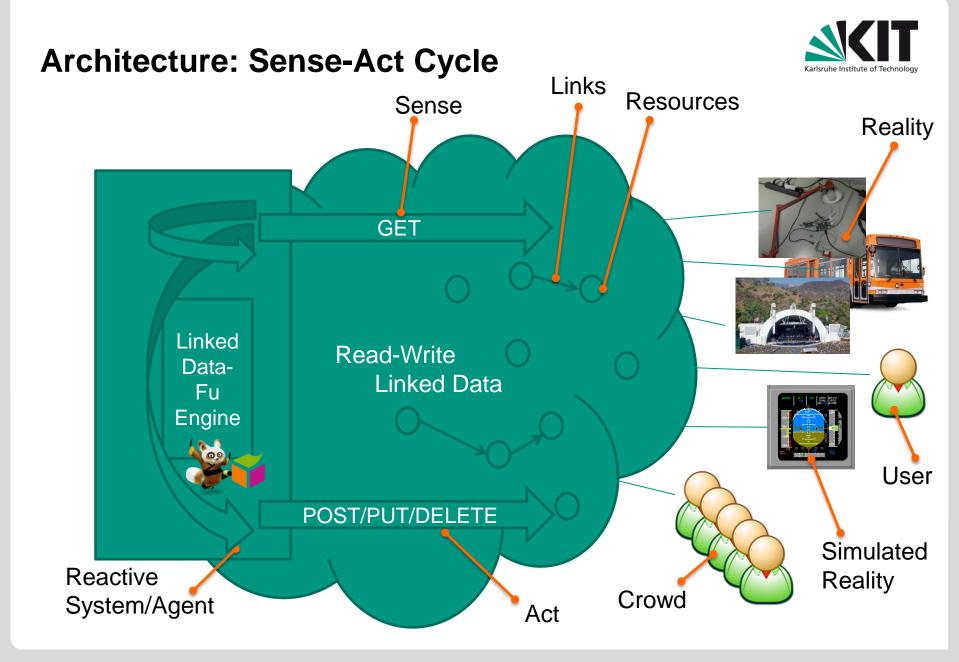
- 1. Use URIs as names for things
- 2. Use HTTP URIs so that people can look up those names.
- 3. When someone looks up a URI, provide useful information, using the standards (RDF*, SPARQL)
- 4. Include links to other URIs. so that they can discover more things.

http://www.w3.org/DesignIssues/LinkedData.html



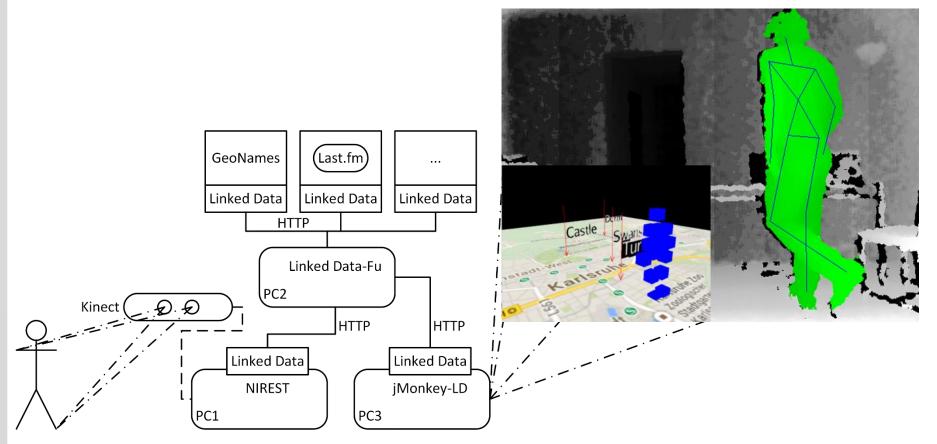
https://en.wikipedia.org/wiki/Robot_Operating_System





Integrating Highly Dynamic RESTful Linked Data APIs in a Virtual Reality Environment





Felix Leif Keppmann, Tobias Käfer, Steffen Stadtmüller, René Schubotz and Andreas Harth. "Integrating Highly Dynamic RESTful Linked Data APIs in a Virtual Reality Environment". International Symposium on Mixed and Augmented Reality (Posters & Demos). ISMAR 2014, Munich, Germany.

Felix Leif Keppmann, Tobias Käfer, Steffen Stadtmüller, René Schubotz and Andreas Harth. "High Performance Linked Data Processing for Virtual Reality Environments". International Semantic Web Conference (Posters & Demos). ISWC 2014, Riva del Garda, Italy.

Conclusion



- Read-Write Linked Data provides a simple and elegant interface to diverse data sources and data sinks with varying update rates
- We are able to scale rule-based system to large number of sources (via hyperlinks – several GBs of data from the LOD cloud) and high update rates (suitable for interactive VR/AR applications)
- We can address industrial use cases with a simple cognitive architecture accessing the environment
- Future work concerns the representation, observation and execution of procedural knowledge