

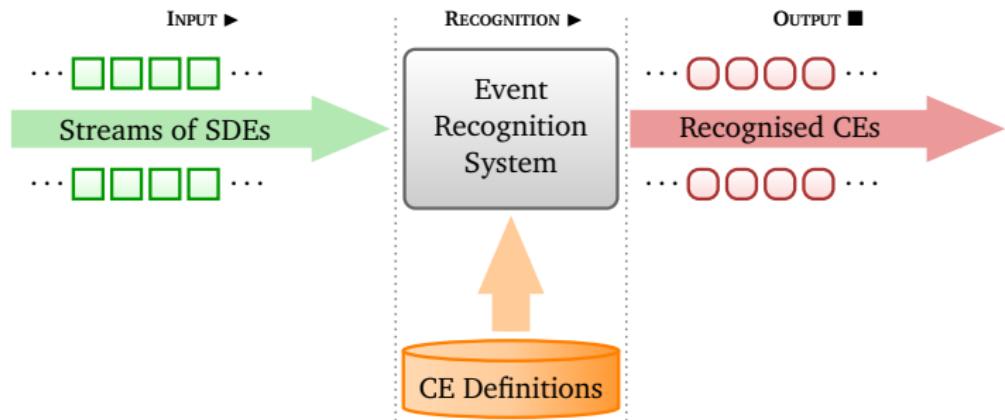
# Event Calculus for Event Recognition

Alexander Artikis

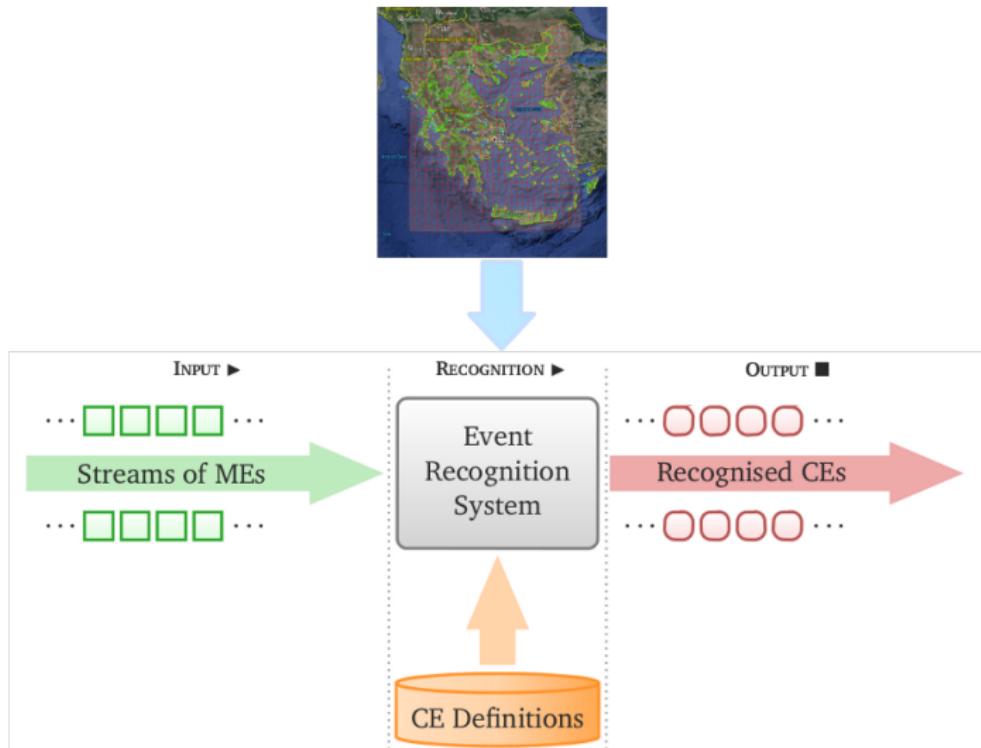
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Athens, Greece

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# Event Recognition



# Event Recognition for Maritime Surveillance



# Fast Approach



- ▶ A vessel is moving at a high speed ...
- ▶ towards another vessel ...
- ▶ (away from ports).

## Possible Rendezvous



- ▶ Two vessels are suspiciously delayed ...
- ▶ in the same location ...
- ▶ at the same time.

## Other Applications

- ▶ City transport & traffic management.
- ▶ Credit card fraud management.
- ▶ Unobtrusive assisted living.
- ▶ Social media verification.
- ▶ Public space surveillance.

# Event Recognition

## Requirements:

- ▶ Efficient reasoning
  - ▶ to support real-time decision-making in large-scale, (geographically) distributed applications.
- ▶ Reasoning under uncertainty
  - ▶ to deal with various types of noise.
- ▶ Automated knowledge construction
  - ▶ to avoid the time-consuming, error-prone manual CE definition development.

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## Event Calculus

- ▶ A logic programming language for representing and reasoning about events and their effects.
- ▶ Key components:
  - ▶ event (typically instantaneous).
  - ▶ fluent: a property that may have different values at different points in time.
- ▶ Built-in representation of **inertia**:
  - ▶  $F = V$  holds at a particular time-point if  $F = V$  has been *initiated* by an event at some earlier time-point, and not *terminated* by another event in the meantime.

# CE Definitions in the Run-Time Event Calculus: Simple Fluents

CE definition:

**initiatedAt**( $CE$ ,  $T$ )  $\leftarrow$   
**happensAt**( $E_{In_1}$ ,  $T$ ),  
[conditions]

...

**initiatedAt**( $CE$ ,  $T$ )  $\leftarrow$   
**happensAt**( $E_{In_i}$ ,  $T$ ),  
[conditions]

**terminatedAt**( $CE$ ,  $T$ )  $\leftarrow$   
**happensAt**( $E_{T_1}$ ,  $T$ ),  
[conditions]

...

**terminatedAt**( $CE$ ,  $T$ )  $\leftarrow$   
**happensAt**( $E_{T_j}$ ,  $T$ ),  
[conditions]

where

conditions:       $^{0-K} \mathbf{happensAt}(E_k, T),$   
                       $^{0-M} \mathbf{holdsAt}(F_m, T),$   
                       $^{0-N} \text{atemporal-constraint}_n$

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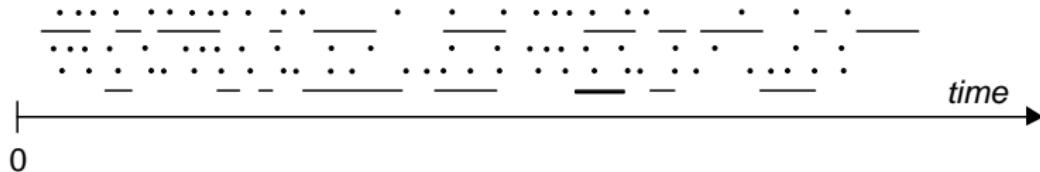
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CE recognition:



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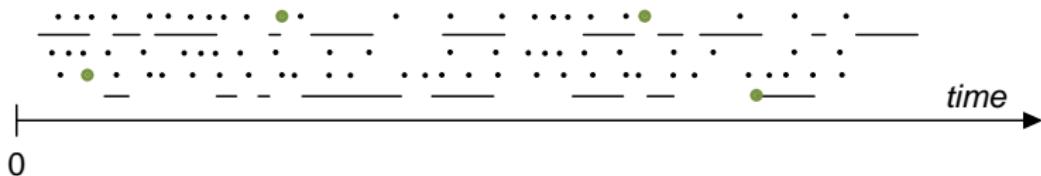
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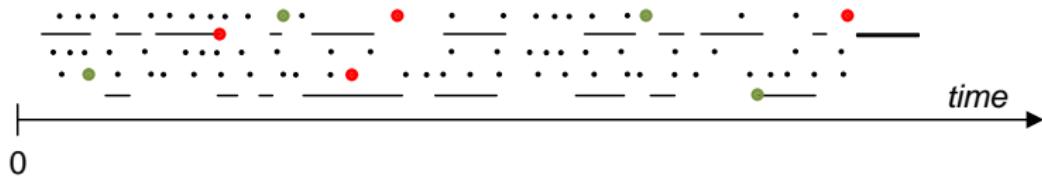
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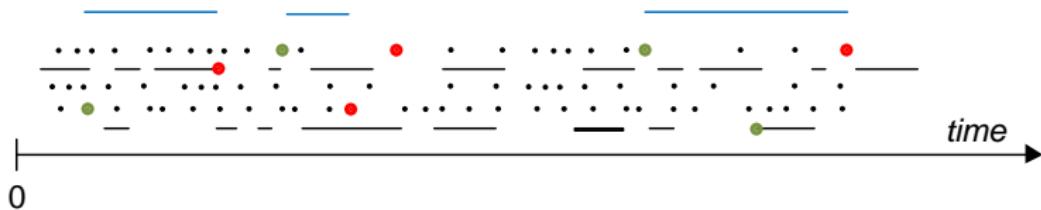
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[conditions]

...

**terminatedAt**( $CE$ ,  $T$ )  $\leftarrow$   
**happensAt**( $E_{T_j}$ ,  $T$ ),  
[conditions]

CE recognition: **holdsFor**( $CE$ ,  $I$ )



# CE Definitions in the Run-Time Event Calculus: Simple Fluents

CE definition:

**initiatedAt**(*suspicious(Area) = true, T*)  $\leftarrow$   
**happensAt**(**start**(*stopped(Vessel) = true, T*)),  
**holdsAt**(*coord(Vessel) = (Lon, Lat, T)*),  
*close(Lon, Lat, Area)*,  
**holdsAt**(*vesselsStoppedIn(Area) = N, T*),  $N > 3$   
**terminatedAt**(*suspicious(Area) = true, T*)  $\leftarrow$   
**happensAt**(**end**(*stopped(Vessel) = true, T*)),  
**holdsAt**(*coord(Vessel) = (Lon, Lat, T)*),  
*close(Lon, Lat, Area)*,  
**holdsAt**(*vesselsStoppedIn(Area) = N, T*),  $N \leq 3$

CE recognition: **holdsFor**(*suspicious(Area) = true, I*)

# CE Definitions in the Run-Time Event Calculus: Statically Determined Fluents

CE definition:

```
holdsFor(CE, I) ←  
  holdsFor(F1, IF1),  
  ...,  
  holdsFor(Ff, IFf),  
  interval_manipulation1(Iα, ..., Iω),  
  ...,  
  interval_manipulationk(IA, ..., IΩ)
```

where

$$\begin{aligned} \textit{interval\_manipulation}(I_1, \dots, I_n) : \\ I_1 \cup \dots \cup I_n \\ I_1 \cap \dots \cap I_n \\ I_1 \setminus I_2 \end{aligned}$$

## CE Definitions in the Run-Time Event Calculus: Statically Determined Fluents

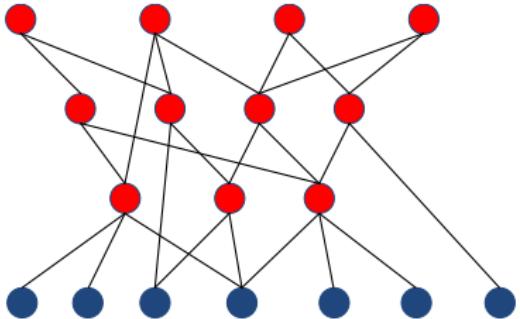
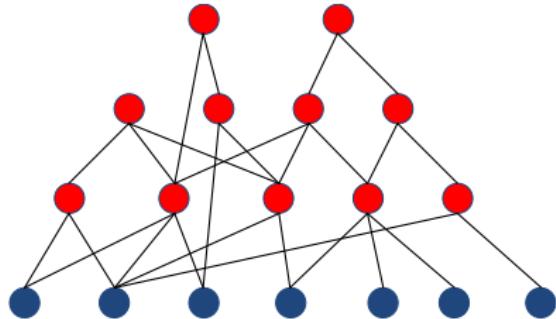
CE definition:

*suspicious( Vessel<sub>1</sub>, Vessel<sub>2</sub>) iff*  
*abnormal( Vessel<sub>1</sub>),*  
*abnormal( Vessel<sub>2</sub>),*  
*close( Vessel<sub>1</sub>, Vessel<sub>2</sub>),*  
*not (in( Vessel<sub>1</sub>, Area) or in( Vessel<sub>2</sub>, Area))*

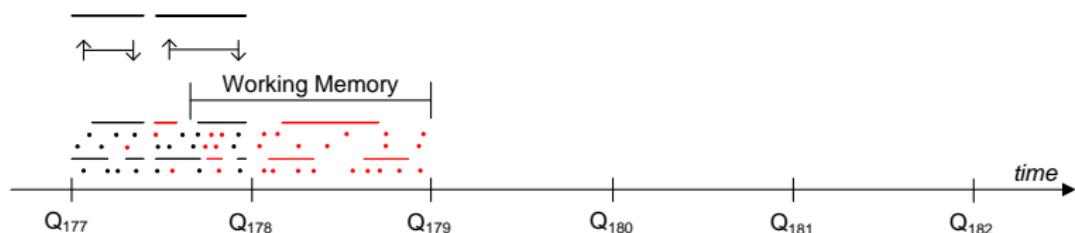
Compiled CE definition:

**holdsFor**(*suspicious( Vessel<sub>1</sub>, Vessel<sub>2</sub>) = true, (I<sub>1</sub> ∩ I<sub>2</sub> ∩ I<sub>3</sub>) \ (I<sub>4</sub> ∪ I<sub>5</sub>)*) ←  
**holdsFor**(*abnormal( Vessel<sub>1</sub>) = true, I<sub>1</sub>*),  
**holdsFor**(*abnormal( Vessel<sub>2</sub>) = true, I<sub>2</sub>*),  
**holdsFor**(*close( Vessel<sub>1</sub>, Vessel<sub>2</sub>) = true, I<sub>3</sub>*),  
**holdsFor**(*in( Vessel<sub>1</sub>, Area) = true, I<sub>4</sub>*),  
**holdsFor**(*in( Vessel<sub>2</sub>, Area) = true, I<sub>5</sub>*)

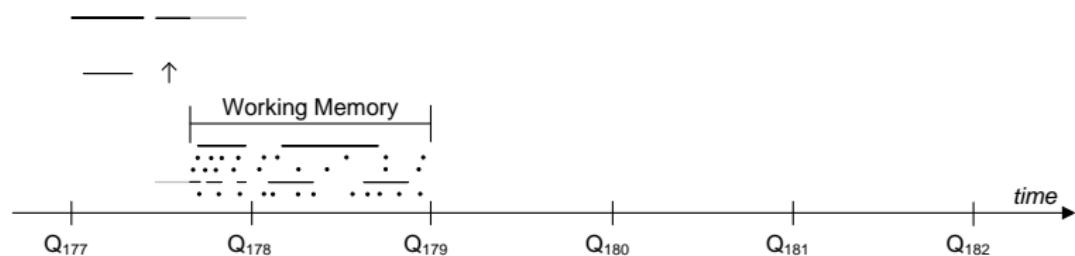
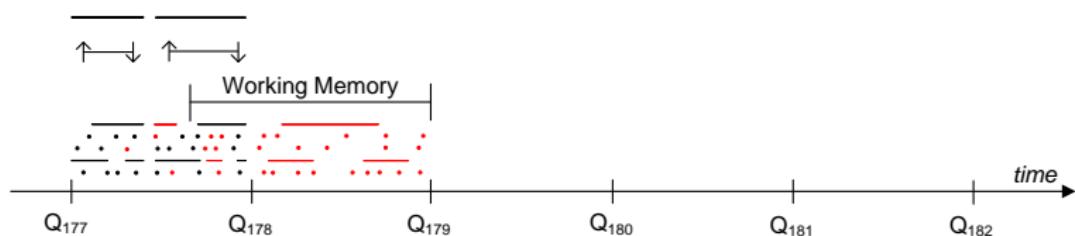
# CE Hierarchies



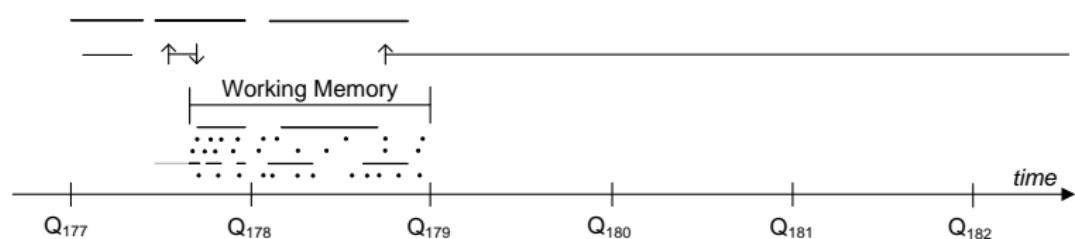
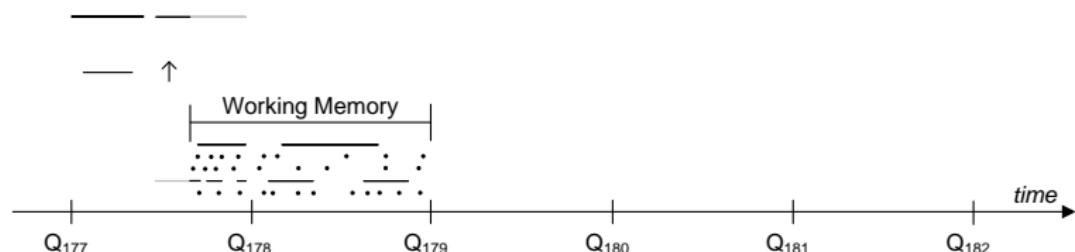
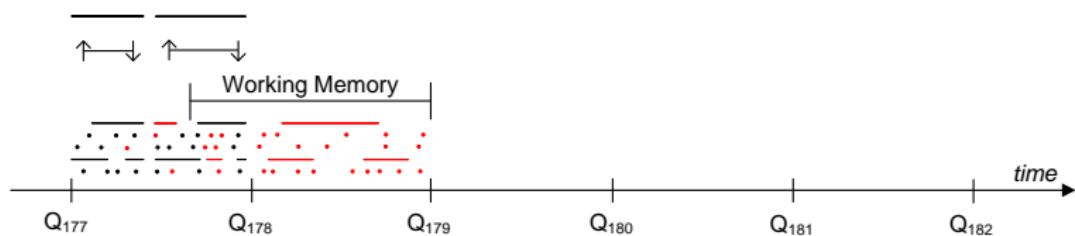
# Run-Time Event Calculus



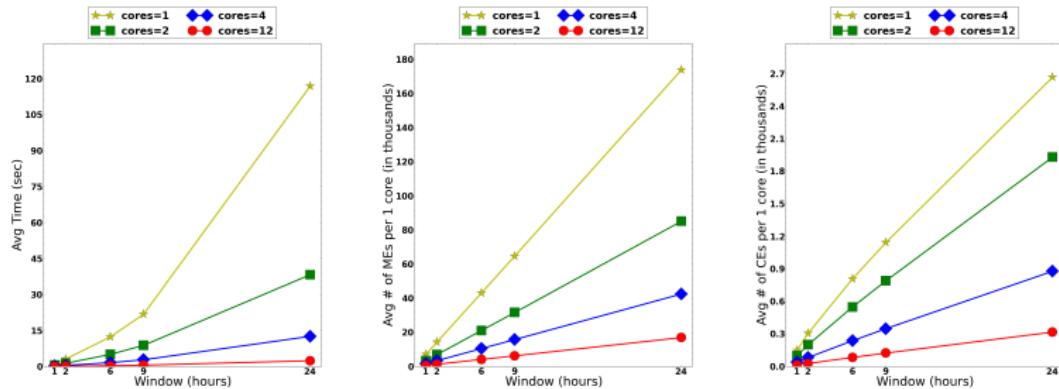
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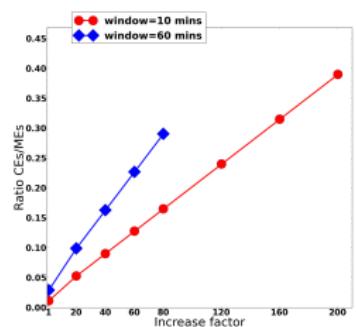
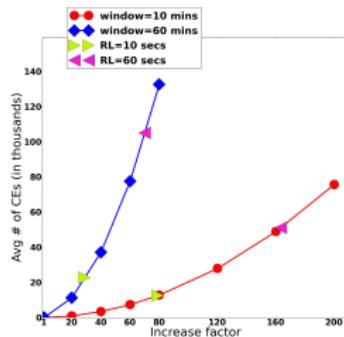
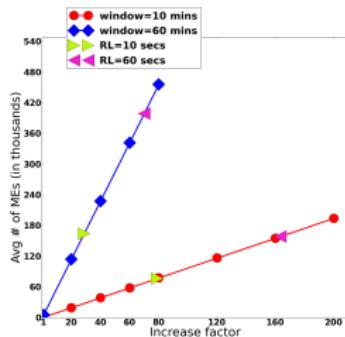
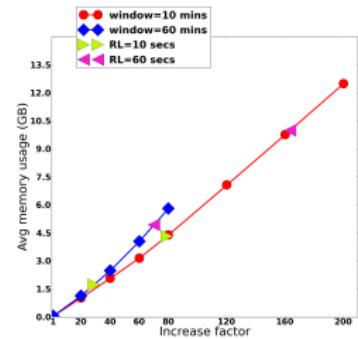
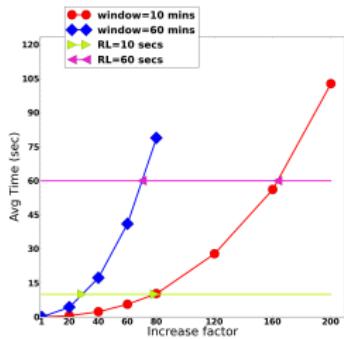


# Empirical Analysis: Maritime Surveillance



- ▶ June–August 2009.
- ▶ >6K vessels sailing in the Greek seas.
- ▶ >4K areas of interest/polygons (1K sides per polygon).
- ▶ >15M streaming **critical** movement events.
- ▶ CE recognition requires complex spatio-temporal reasoning.

# Big Maritime Data: x200 Larger Datasets

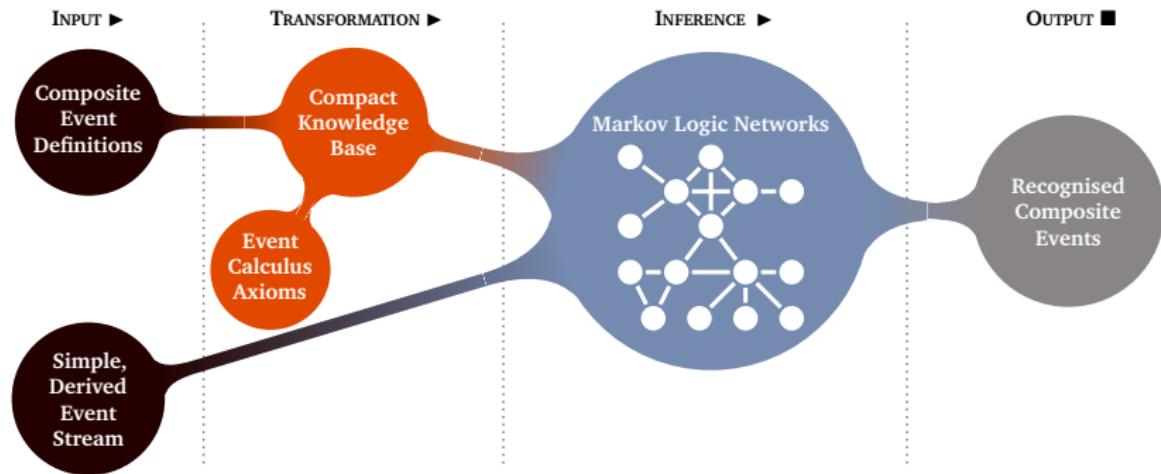


# Event Recognition

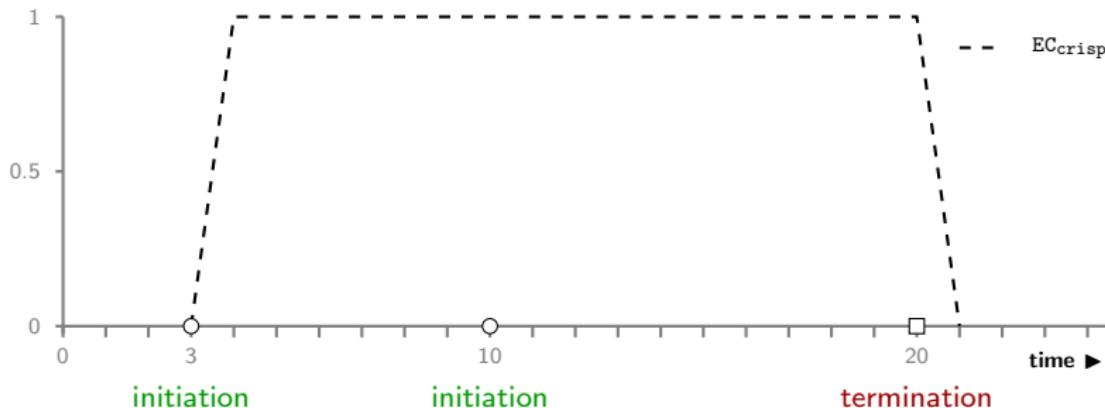
## Requirements:

- ▶ Efficient reasoning
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- ▶ Automated knowledge construction
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# Probabilistic Event Calculus based on Markov Logic Networks (MLN-EC)



# MLN-EC: Inertia



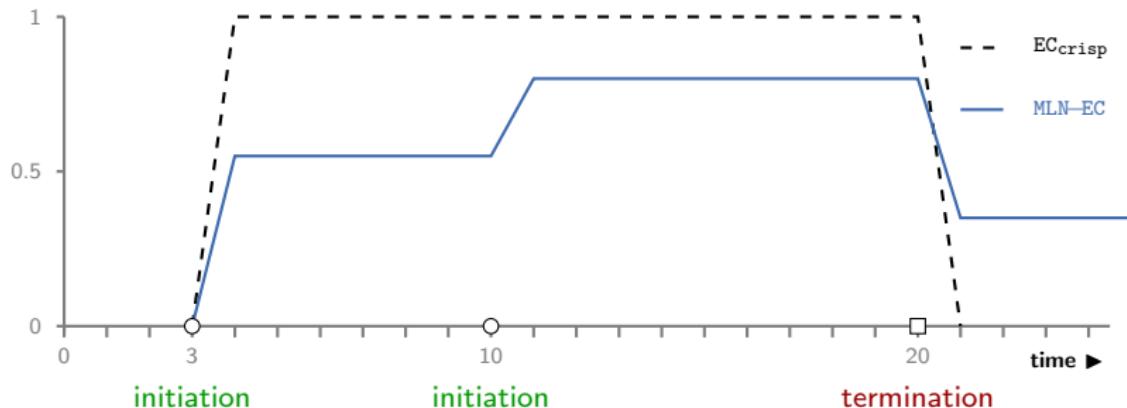
$\infty \quad holdsAt(CE, T+1) \Leftarrow [Initiation\ Conditions]$

$\infty \quad \neg holdsAt(CE, T+1) \Leftarrow \neg holdsAt(CE, T) \wedge \neg [Initiation\ Conditions]$

$\infty \quad \neg holdsAt(CE, T+1) \Leftarrow [Termination\ Conditions]$

$\infty \quad holdsAt(CE, T+1) \Leftarrow holdsAt(CE, T) \wedge \neg [Termination\ Conditions]$

# MLN-EC: Inertia



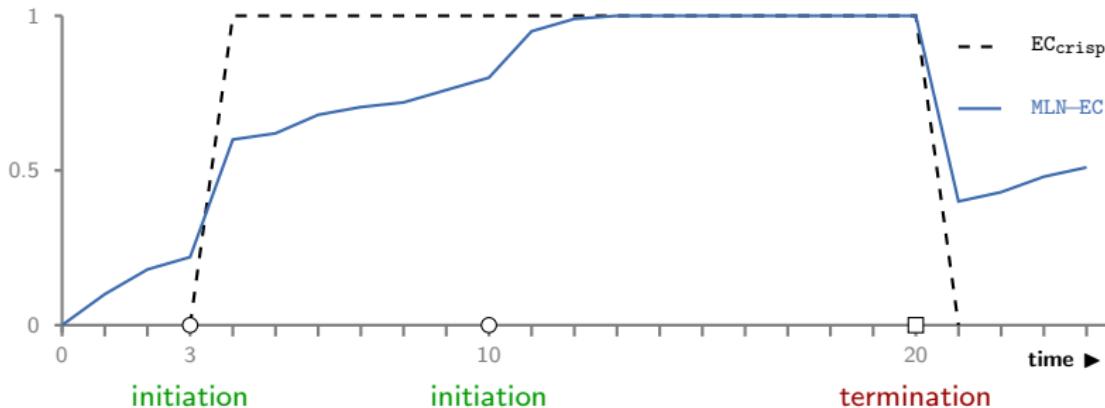
1.2  $\text{holdsAt}(\text{CE}, T+1) \Leftarrow$   
[Initiation Conditions]

$\infty \quad \neg \text{holdsAt}(\text{CE}, T+1) \Leftarrow$   
 $\neg \text{holdsAt}(\text{CE}, T) \wedge$   
 $\neg$  [Initiation Conditions]

0.7  $\neg \text{holdsAt}(\text{CE}, T+1) \Leftarrow$   
[Termination Conditions]

$\infty \quad \text{holdsAt}(\text{CE}, T+1) \Leftarrow$   
 $\text{holdsAt}(\text{CE}, T) \wedge$   
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# MLN-EC: Inertia



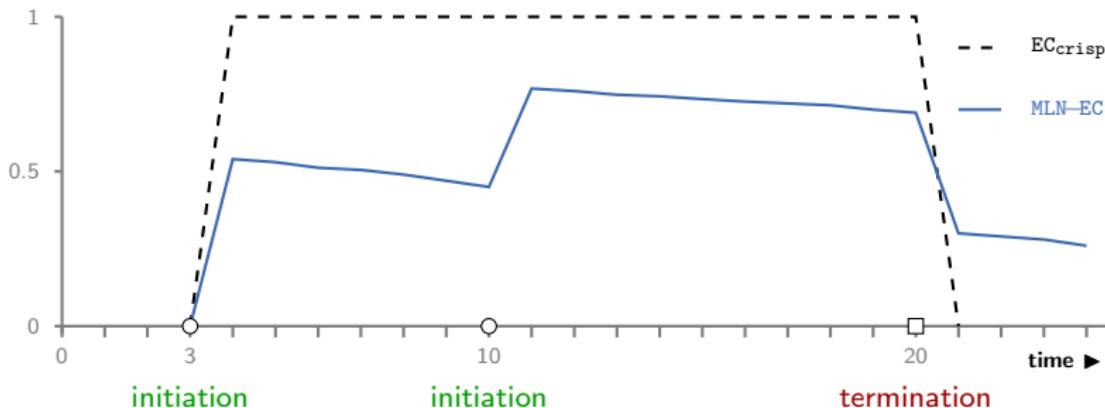
1.2  $\text{holdsAt}(\text{CE}, T+1) \Leftarrow$   
[Initiation Conditions]

2.3  $\neg\text{holdsAt}(\text{CE}, T+1) \Leftarrow$   
 $\neg\text{holdsAt}(\text{CE}, T) \wedge$   
 $\neg$ [Initiation Conditions]

0.7  $\neg\text{holdsAt}(\text{CE}, T+1) \Leftarrow$   
[Termination Conditions]

$\infty$   $\text{holdsAt}(\text{CE}, T+1) \Leftarrow$   
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# MLN-EC: Inertia



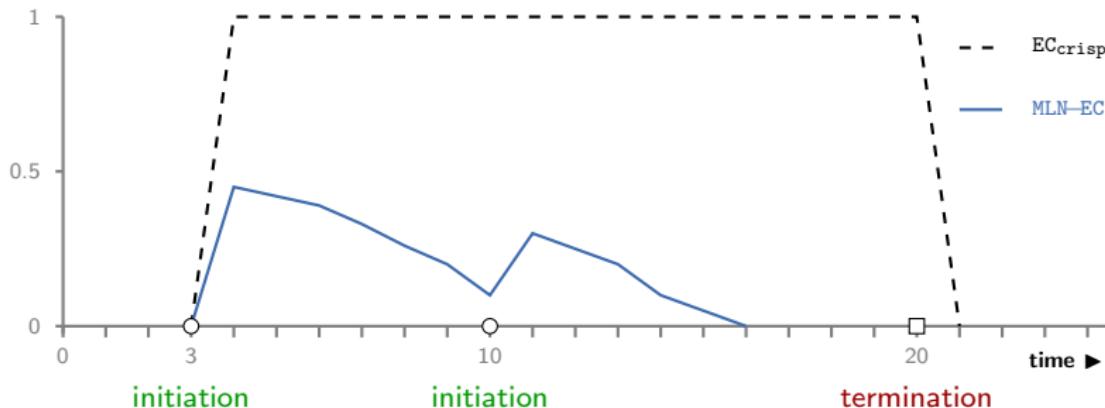
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# MLN-EC: Inertia



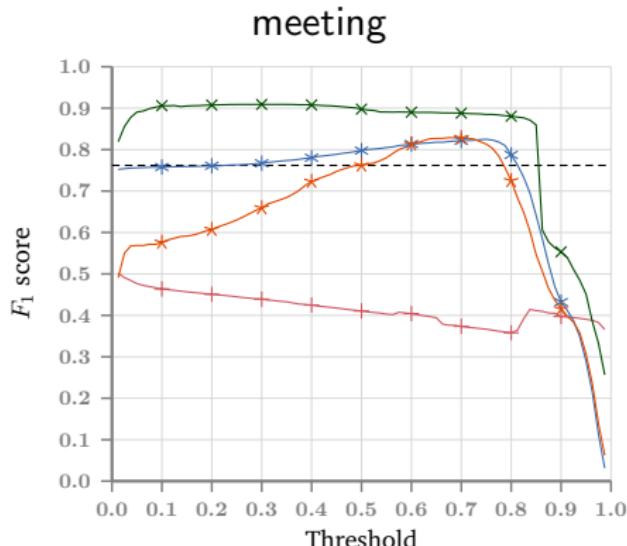
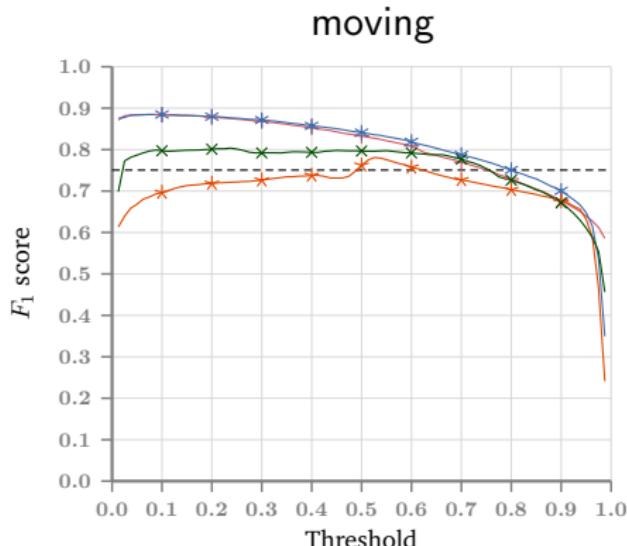
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0.7  $\neg \text{holdsAt}(\text{CE}, \text{T}+1) \Leftarrow$   
[Termination Conditions]

0.6  $\text{holdsAt}(\text{CE}, \text{T}+1) \Leftarrow$   
 $\text{holdsAt}(\text{CE}, \text{T}) \wedge$   
 $\neg$  [Termination Conditions]

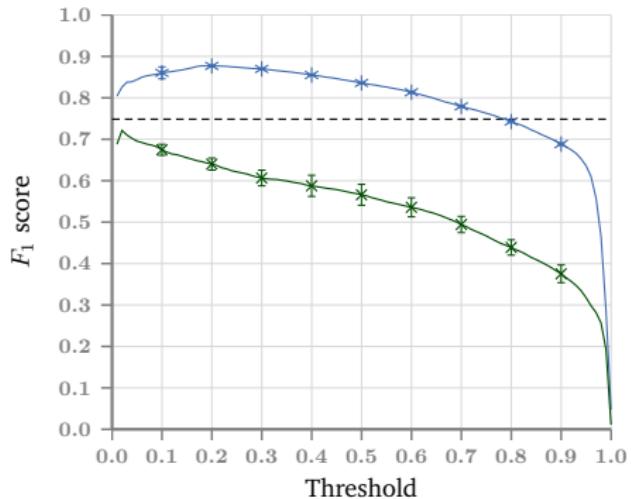
# MLN-EC: Complete data (marginal inference)



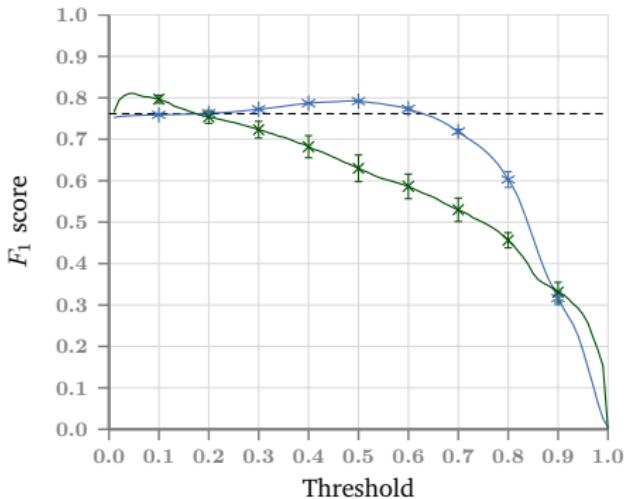
- EC<sub>crisp</sub> : Crisp Event Calculus
- ★- 1-CRF : Linear-chain Conditional Random Field
- +-- MLN-EC<sub>HI</sub> : Hard-constrained inertia
- \*- MLN-EC<sub>SIT</sub> : Soft-constrained termination inertial rules
- ★- MLN-EC<sub>SI</sub> : Soft-constrained inertial rules

# MLN-EC: Incomplete data (marginal inference)

moving



meeting



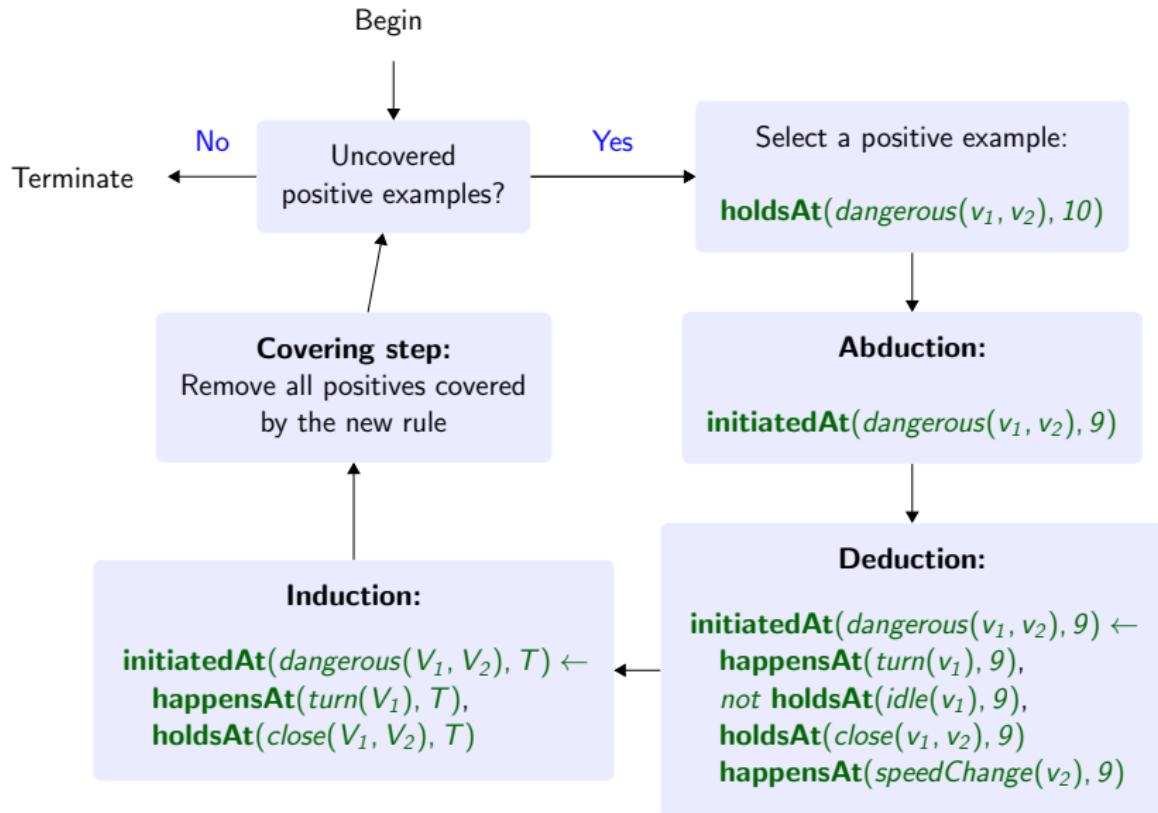
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# eXtended Hybrid Abductive-Inductive Learning – XHAIL



# Incremental Learning

Given:

- ▶ A SDE stream  $\mathcal{E}$  annotated with CE (historical memory).
- ▶ A CE definition  $H$  which is **correct** w.r.t  $\mathcal{E}$ .
- ▶ A new SDE batch in which  $H$  is **incorrect**.

Historical Memory  $\mathcal{E}$



$H :$

```
initiatedAt(dangerous(V1, V2), T) ←
  happensAt(turn(V1), T),
  holdsAt(idle(V2), T)
```

# Incremental Learning

Goal:

- ▶ Revise  $H$  to an  $H'$  that is correct w.r.t all examples.

Historical Memory  $\mathcal{E}$

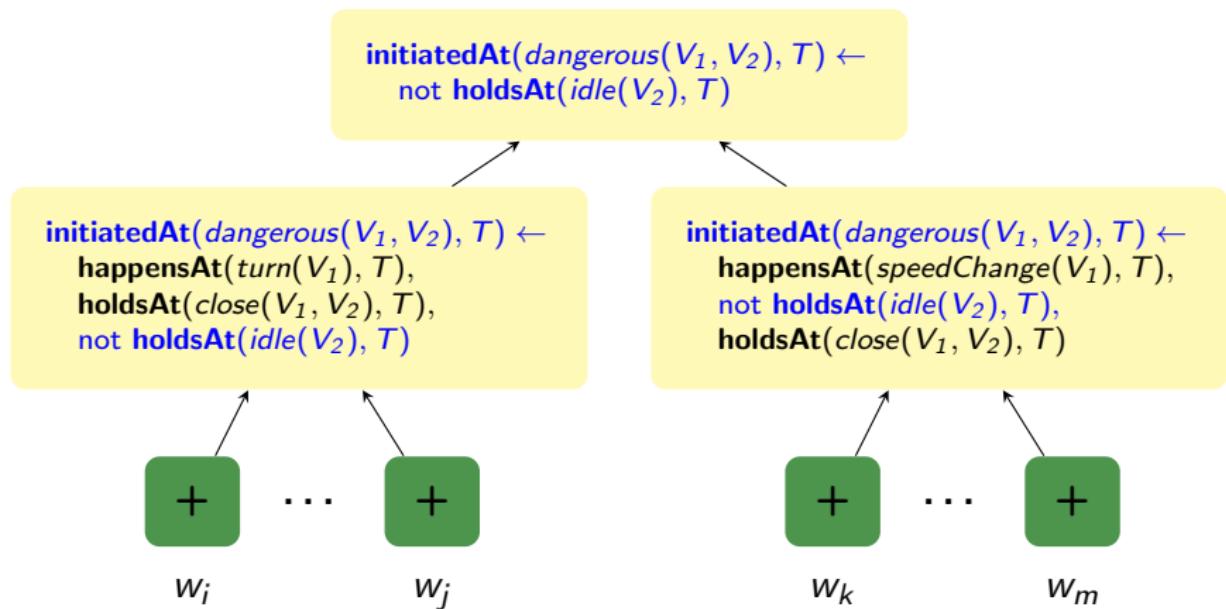


$H'$  :

```
initiatedAt(dangerous(V1, V2), T) ←  
    happensAt(turn(V1), T),  
    not holdsAt(idle(V2), T),  
    holds(close(V1, V2), T)  
  
initiatedAt(dangerous(V1, V2), T) ←  
    happensAt(speedChange(V1), T),  
    not holdsAt(idle(V2), T),  
    holdsAt(close(V1, V2), T)
```

# Efficient Incremental Learning: Support Set

- ▶ While constructing a CE definition, summarise the positive examples it covers so far.
- ▶ Use this memory for specialisation without having to look back.
  - ▶ Reject negatives locally, preserve positives globally.



## Evaluation: ILED vs XHAIL

Granularity $G$	ILED			XHAIL (1 batch)
	$G = 10$	$G = 50$	$G = 100$	$G = 1000$
Training Time (sec)	34.15	23.04	286.74	1560.88
Revisions	11.2	9.1	5.2	—
Hypothesis size	17.82	17.54	17.5	15
Precision	98.713	99.767	99.971	99.973
Recall	99.789	99.845	99.988	99.992

## Resources

- ▶ Run-Time Event Calculus (RTEC):
  - ▶ Alexander Artikis, Marek J. Sergot, Georgios Paliouras: An Event Calculus for Event Recognition. IEEE Transactions on Knowledge & Data Engineering 27(4): 895-908 (2015)
  - ▶ <https://github.com/aartikis/RTEC>
- ▶ Event Calculus in Markov Login Networks (LoMRF):
  - ▶ Anastasios Skarlatidis, Georgios Paliouras, Alexander Artikis, George A. Vouros: Probabilistic Event Calculus for Event Recognition. ACM Transactions on Computational Logic 16(2): 11:1-11:37 (2015)
  - ▶ <https://github.com/anskarl/LoMRF>
- ▶ Incremental Learning of Event Definitions (ILED):
  - ▶ Nikos Katzouris, Alexander Artikis, Georgios Paliouras: Incremental learning of event definitions with Inductive Logic Programming. Machine Learning 100(2-3): 555-585 (2015)
  - ▶ <https://github.com/nkatzz/ILED>
- ▶ Further info: <http://cer.iit.demokritos.gr>